

melanogaster (U37541), mosquito *Anopheles quadrimaculatus* (L04272), mosquito *Anopheles gambiae* (L20934), medfly *Ceratitis capitata* (CCA242872), *Cochliomyia hominivorax* (AF260826), locust *Locusta migratoria* (X80245), honey bee *Apis mellifera* (L06178), brine shrimp *Artemia franciscana* (X69067), water flea *Daphnia pulex* (AF117817), shrimp *Penaeus monodon* (AF217843), hermit crab *Pagurus longicarpus* (AF150756), horseshoe crab *Limulus polyphemus* (AF216203), tick *Ixodes hexagonus* (AF081828), tick *Rhipicephalus sanguineus* (AF081829). For outgroup comparison, sequences were retrieved for the annelid *Lumbricus terrestris* (U24570), the mollusc *Katharina tunicata* (U09810), the nematodes *Caenorhabditis elegans* (X54252), *Ascaris suum* (X54253), *Trichinella spiralis* (AF293969) and *Onchocerca volvulus* (AF015193), and the vertebrate species *Homo sapiens* (J01415) and *Xenopus laevis* (M10217). Additional sequences were analysed for gene arrangements: *Boophilus microplus* (AF110613), *Euhadra herklotsi* (Z71696), *Cepaea nemoralis* (U23045) and *Pupa strigosa* (NC_002176).

Multiple alignments were prepared for all putative protein sequences using Clustal W²⁴ at default settings. Consistent with previous studies²⁵, preliminary analyses revealed obvious tree estimation artefacts due to extremely accelerated substitution rates or protein composition bias in the nematode species, the honeybee *Apis mellifera* and the tick species *Rhipicephalus sanguineus* and *Ixodes hexagonus*. With the exception of *Ixodes hexagonus* all of these taxa were therefore excluded from further analyses, reducing the total number of species considered to 18. Sequence alignment was repeated and inspected by eye for sufficient levels of sequence conservation, which resulted in the exclusion of the ATPase 8 gene (see Supplementary Information for single protein alignments). We used Gblocks²⁶ to extract regions of defined sequence conservation from the gene specific alignments and generate a single file of concatenated conserved regions. Default settings yielded the 18P2560 alignment. Modified parameter settings for generating the 18P1528 alignment were: minimum number of sequences for a conserved position: 15; maximum number of contiguous nonconserved positions: 2; minimum length of a block after gap cleaning: 5. Alignments can be retrieved from the EBI webserver (<ftp://ftp.ebi.ac.uk/pub/databases/emb/align>) under accession numbers ALIGN_000111 and ALIGN_000112. Maximum-likelihood mapping was carried out as described in ref. 16. Pairwise relative rate tests were carried out with the Hy-Phy program package²⁷. Protein composition homogeneity test and maximum likelihood tree estimation was carried out using the TREE-PUZZLE program²⁸ applying the mtREV24 sequence evolution model for mitochondrial proteins²⁹ and a four rate approximated gamma distribution of among-site rate heterogeneity. Maximum-likelihood trees were determined by likelihood ratio tests between competing topologies. Maximum-parsimony tree reconstruction and neighbour-joining analysis with Dayhoff PAM matrix distances were performed using the respective algorithms implemented in Phylip 3.5 (ref. 30). Non-parametric bootstrapping analyses were based on 100 replicate data sets.

Received 22 February; accepted 13 July 2001.

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Supplementary information is available from Nature's World-Wide Website (<http://www.nature.com>) or as paper copy from the London editorial office of Nature.

Acknowledgements

We thank N. Muqim for technical assistance and A. Minelli and T. Burmester for comments on the manuscript. Most computation was performed on the Biological Software Server of the Institute Pasteur Paris. This study was in part supported by a DFG grant to D.T. and a Brain Korea 21 Project grant to W.K. U.W.H. was supported by fellowships from Deutscher Akademischer Austauschdienst, Korea Science and Engineering Foundation, and the Brain Korea 21 Project (Medical Sciences, Yonsei University).

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Arthropod phylogeny based on eight molecular loci and morphology

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The interrelationships of major clades within the Arthropoda remain one of the most contentious issues in systematics, which has traditionally been the domain of morphologists^{1,2}. A growing body of DNA sequences and other types of molecular data has revitalized study of arthropod phylogeny^{3–7} and has inspired new considerations of character evolution^{8,9}. Novel hypotheses such as a crustacean–hexapod affinity^{4,10–12} were based on analyses of single or few genes and limited taxon sampling, but have received recent support from mitochondrial gene order¹³, and eye and brain ultrastructure and neurogenesis^{14,15}. Here we assess relationships within Arthropoda based on a synthesis of all well sampled molecular loci together with a comprehensive data set of morphological, developmental, ultrastructural and gene-order characters. The molecular data include sequences of three nuclear ribosomal genes, three nuclear protein-coding genes, and two mitochondrial genes (one protein coding, one ribosomal). We devised new optimization procedures^{16,17} and constructed a parallel computer cluster with 256 central processing units¹⁸ to analyse molecular data on a scale not previously possible. The optimal 'total evidence' cladogram supports the crustacean–hexapod clade, recognizes pycnogonids as sister to other euarthropods, and indicates monophyly of Myriapoda and Mandibulata.

Based on morphological evidence, neontological^{1,5,6} and palaeontological² hypotheses regarding deep divergences within Arthropoda differ in the monophyly of Mandibulata (arthropods with mandibles: crustaceans, myriapods and hexapods) versus

Schizoramia (arthropods with biramous appendages: crustaceans and stem-group chelicerates). Both fields have traditionally agreed that atelocerates (myriapods and hexapods) constitute a natural group. The Pancrustacea¹⁹ hypothesis challenges a myriapod–hexapod alliance, instead resolving crustaceans as the closest relatives of hexapods. Only by combining all of the available data can the competing hypotheses be compared effectively for their ability to explain the evolution of the diverse sorts of changes that have occurred in many aspects of arthropod biology. Simultaneous analyses of morphological and molecular data addressed early conflicts of character data quality in arthropod evolution^{3,5,6,20}. The investigation of a few more gene systems^{12,21,22} complemented the widely used set of nuclear ribosomal genes^{5,7,10}. However, to our knowledge, synthetic work combining multiple sources of molecular information, together with morphological data, has been restricted in either taxonomic or locus sampling.

We analysed sequence data of three nuclear ribosomal genes (18S ribosomal RNA, the D3 region of 28S rRNA, and the small nuclear rRNA U2), three nuclear protein-coding genes (histone H3, elongation factor-1 α and the largest subunit of RNA polymerase II), and

two mitochondrial loci, one protein coding (cytochrome *c* oxidase I) and one ribosomal (16S rRNA). From these data, six loci have been mostly sequenced in ours and co-workers' laboratories, and the remaining two genes (elongation factor-1 α and RNA polymerase II) were obtained from GenBank (see Table 1). The sequence data comprise about 5 kilobases (kb) of nucleotide information. We chose these genes because of their dense taxonomic sampling and because they have been reported to resolve phylogenetic history at different taxonomic levels, so we expected their levels of resolution to overlap.

Non-sequence data analyses for arthropod interrelationships are few, and all rely on groundplan coding, a strategy that tends to standardize states within 'known' morphologically defined groups. This coding strategy tends to generate phylogenetic trees in agreement with classical hypotheses, but represents a biased test for relationships. On the contrary, if character states are scored only for those taxa for which real observations have been made, missing data (unknown states) may proliferate, which more accurately represents the actual knowledge of the group. Following the logic of this coding strategy, we modified, expanded and reanalysed a published

Table 1 Taxonomic categories represented in the trees, exemplar species and genes sequenced for each terminal

Peripatopsidae	<i>Euperipatoides/Peripatopsis</i>	18S	28S	H3	U2	EF	POL	COI	
Peripatidae	<i>Epiperipatus/Oroperipatus</i>	18S		H3	U2	EF	POL	COI	
Eutardigrada	<i>Macrobiotus/Milnesium</i>	18S			U2	EF	POL		
PYCNOGONIDA									
<i>Endeis</i>	<i>Endeis laevis</i>	18S	28S			EF	POL	COI	
<i>Colossendeis</i>	<i>Colossendeis</i> sp.	18S	28S			EF	POL	COI	
Ammotheidae	<i>Achelia/Ammothella/Tanystylum</i>	18S	28S	H3	U2	EF	POL	COI	16S
EUCHELICERATA									
<i>Limulus</i>	<i>Limulus polyphemus</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Carcinoscorpius</i>	<i>Carcinoscorpius rotundicaudus</i>	18S	28S	H3	U2	EF	POL	COI	16S
Buthidae	<i>Androctonus/Lychas</i>	18S	28S	H3	U2			COI	16S
<i>Mastigoproctus</i>	<i>Mastigoproctus giganteus</i>	18S	28S			EF	POL	COI	16S
Mygalomorphae	<i>Atrax/Aphonopelma</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Opilio</i>	<i>Opilio paretinus</i>	18S	28S					COI	16S
<i>Nipponopsalis</i>	<i>Nipponopsalis abei</i>	18S	28S			EF	POL		
Laniatores	<i>Equitius/Vonones/Dalquestia</i>	18S	28S	H3	U2	EF	POL	COI	
MYRIAPODA									
Scutigeridae	<i>Allothereua/Scutigera</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Lithobius</i>	<i>L. obscurus/variegatus</i>	18S	28S	H3		EF	POL	COI	16S
<i>Craterostigma</i>	<i>Craterostigma tasmanianus</i>	18S	28S	H3	U2			COI	16S
Scolopendridae	<i>Cormocephalus/Scolopendra/Ethmostigma</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Mecistocephalus</i>	<i>Mecistocephalus</i> sp./tahiensis	18S	28S	H3				COI	16S
Chilenocephalidae	<i>Ribautia/Pachymerium</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Hanseniella</i>	<i>Hanseniella</i> sp.	18S	28S	H3	U2	EF	POL	COI	16S
<i>Scutigera</i>	<i>Scutigera</i> sp.	18S	28S			EF	POL		
Pauropodinae	<i>Pauropodinae</i> sp.	18S	28S	H3	U2				
Polyxenidae	<i>Polyxenus/Unixenus</i>	18S	28S	H3	U2	EF	POL	COI	
Sphaerotheriidae	<i>Cyliosomatini/Epicyliosoma</i> sp.	18S		H3	U2			COI	16S
<i>Proteroiulus</i>	<i>Proteroiulus fuscus</i>	18S	28S			EF	POL	COI	16S
<i>Narceus</i>	<i>Narceus americanus</i>	18S	28S			EF	POL	COI	16S
CRUSTACEA									
Remipedia	<i>Speleonectes/Lasionectes</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Hutchinsoniella</i>	<i>Hutchinsoniella macracantha</i>	18S	28S	H3		EF	POL	COI	16S
Calanoida	<i>Calanus/Eurytemora</i>	18S				EF	POL	COI	16S
Anostraca	<i>Artemia/Branchinella</i>	18S	28S	H3	U2	EF	POL	COI	16S
<i>Triops</i>	<i>T. longicaudatus/australiensis</i>	18S		H3	U2	EF	POL	COI	16S
<i>Limnadia</i>	<i>Limnadia</i> sp./lenticularis	18S				EF	POL		
<i>Daphnia</i>	<i>Daphnia galeata/pulex</i> /sp.	18S			U2			COI	16S
<i>Nebalia</i>	<i>Nebalia</i> sp./longicornis/hessleri	18S	28S	H3	U2	EF	POL	COI	
Balanidae	<i>Balanus/Semibalanus</i>	18S	28S	H3	U2	EF	POL	COI	
Stomatopoda	<i>Kempina mikado/Gonodactylus</i>	18S		H3	U2			COI	16S
<i>Anaspides</i>	<i>Anaspides tasmaniae</i>	18S	28S					COI	16S
Oniscidea	<i>Armadillidium/Trichoniscus/Australophiloscia</i>	18S	28S			EF	POL	COI	16S
Reptantia	<i>Homarus americanus/Libinia</i>	18S	28S	H3	U2	EF		COI	16S
HEXAPODA									
Protura	<i>Acerenthus/Nipponentomon/Acerentomon</i>	18S	28S	H3		EF			
Arthropleona	<i>Podura/Archisotoma/Tomocerus</i>	18S	28S	H3	U2	EF	POL	COI	16S
Campodeidae	<i>Campodea/Eumesocampa</i>	18S	28S	H3		EF	POL	COI	16S
Japygidae	<i>Catapyx/Metajapyx/Heterojapyx</i>	18S	28S			EF	POL	COI	16S
Meinertellidae	<i>Allomachilis/Machiloides</i>	18S	28S	H3	U2	EF	POL	COI	16S
Machilidae	<i>Dilta/Petrobiinae/Pedetontus</i>	18S	28S	H3		EF	POL	COI	16S
<i>Tricholepidion</i>	<i>Tricholepidion gertschii</i>	18S	28S	H3	U2				
Lepismatidae	<i>Thermobia/Ctenolepisma</i>	18S	28S			EF	POL	COI	16S
<i>Callibaetis</i>	<i>Callibaetis ferrugineus</i>	18S		H3	U2			COI	16S
<i>Periplaneta</i>	<i>Periplaneta americana</i>	18S		H3	U2	EF	POL	COI	
<i>Locusta</i>	<i>Locusta migratoria</i>	18S	28S	H3	U2			COI	16S
<i>Drosophila</i>	<i>Drosophila melanogaster</i>	18S	28S	H3	U2	EF	POL	COI	16S

The taxonomic category listed is the least inclusive for the species for which molecular data have been obtained. More details on exact GenBank numbers for each partition, fragments analysed and batch files for the analyses is provided as Supplementary Information.

morphology data set⁶ in order to code the non-sequence (morphological and gene order) features of 51 terminals (2 onychophoran, 1 tardigrade and 48 arthropod lineages) for which at least four of the eight selected loci were available. A total of 303 characters was employed (see Supplementary Information).

The principle of total evidence is an important maxim in phylogenetic systematics because alternatives to using all available evidence must explicitly exclude parts of the data²³. Excluding data *a priori* biases the outcome towards the set of characters retained. Combining all sources of molecular information with non-sequence characters allows phylogenetic hypotheses to be formulated based on a maximum number of independent data points and thus provides the greatest explanatory power.

The shortest cladograms based on the morphology and gene-order data alone recognize Mandibulata, Crustacea and Hexapoda as well supported clades (Bremer support ≥ 6). A sister-group relationship between Hexapoda and monophyletic Myriapoda is weakly favoured over the alternative grouping of Crustacea and Hexapoda, one step separating these hypotheses. The tree resulting from the combined analysis of all sources of data for the parameter set that minimizes overall incongruence among data partitions (using a character-based congruence metric as an optimality criterion²⁴) shows monophyly of arthropods (Fig. 1). Pycnogonids are a sister group to all other euarthropods, as is also resolved based on the non-sequence data alone. Chelicerata (horseshoe crabs and arachnids) and Mandibulata are sister taxa within the

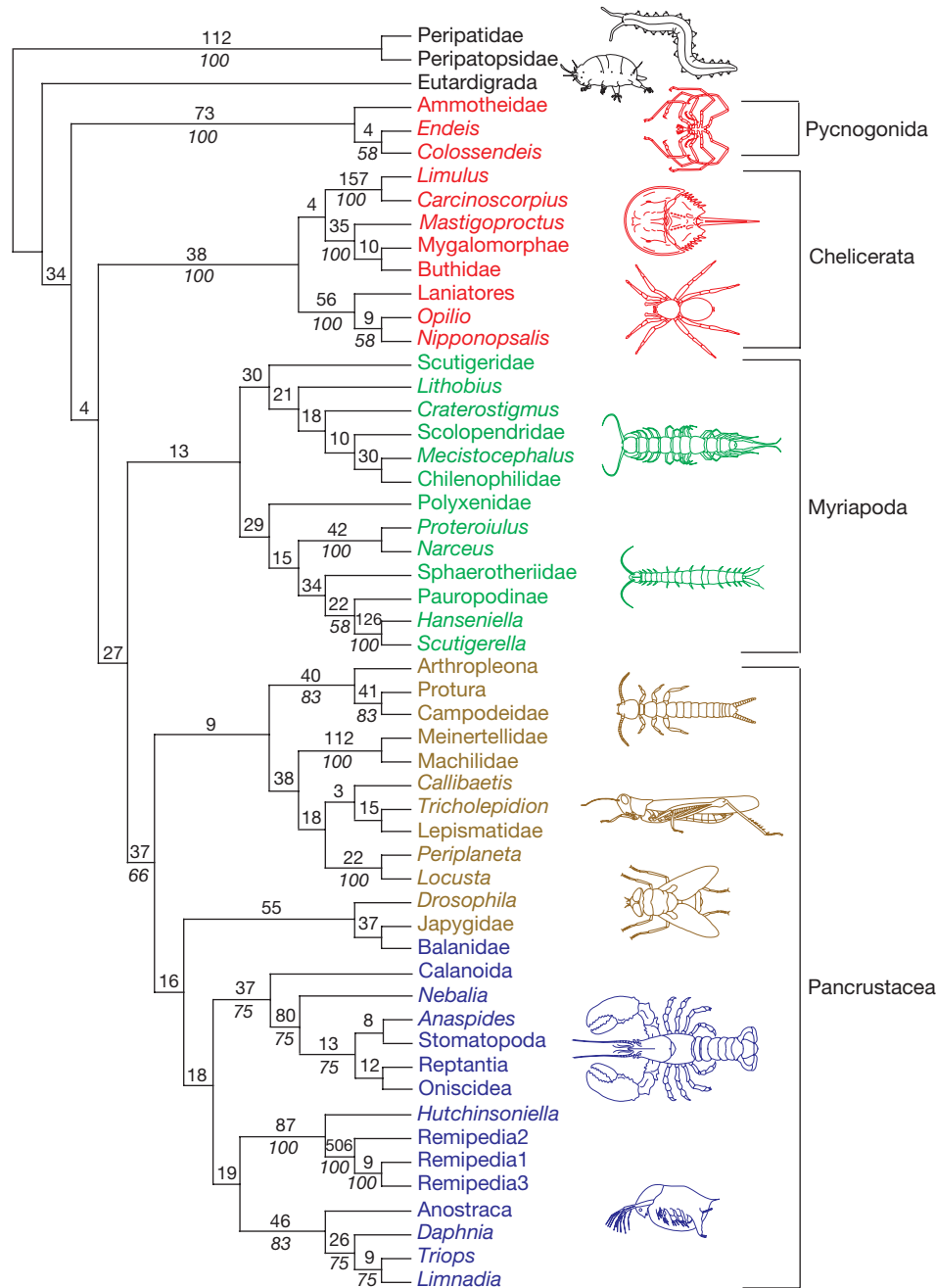


Figure 1 Phylogenetic tree of arthropod lineages based on DNA sequence data of eight loci and 303 characters of non-sequence data for the parameter set that minimizes overall incongruence among the nine partitions. The single tree, obtained when insertions and deletions equal all other genetic changes, requires 27,375 steps. Bremer support

values are shown above branches while percentage of analytical parameters yielding a given topology are represented in italics. 'Chelicerates', myriapods, hexapods and crustaceans are displayed in red, green, brown and blue, respectively.

Euarthropoda. The data support neither a monophyletic Schizoramia (chelicerates + crustaceans) nor a clade composed exclusively of chelicerates and myriapods.

A monophyletic group is formed by myriapods, crustaceans and hexapods, a resolution that is consistent with the origin of mandibles being a unique event during arthropod evolution^{8,9}. Relationships within Mandibulata strongly support the monophyly of Pancrustacea, although support is weak for the monophyly of myriapods. The basic division of Myriapoda into Chilopoda (centipedes) and Progoneata (millipedes, pauropods and symphylans) is retrieved by morphology as well as the combination of all data. Resolution of the internal phylogeny of the centipedes is identical between morphological and total-evidence trees, whereas relationships of the progoneates differ substantially. Inclusion of sequence data serves to unite the Symphyla and Pauropoda, which perturbs the monophyly of Diplopoda (millipedes).

Pancrustacean relationships are confusing in the optimal cladogram based on combined data, because neither crustaceans nor hexapods are strictly monophyletic. *Drosophila* forms a clade with a japygid dipluran (basal hexapod) and a barnacle, and this clade receives a moderately high Bremer support value. However, a clade resolving *Drosophila* with other insects, as expected from the morphological analysis, is found in 91% of the combined analyses (all other parameter sets explored). The aberrant behaviour of *Drosophila* is mainly due to its placement based on the gene fragments of elongation factor-1 α and RNA polymerase II. Unfortunately *Drosophila* was not included in previous analyses with these gene fragments.

Crustacea is monophyletic in the non-sequence data analysis as well as in 50% of the combined analyses performed for the different parameter sets. Under the remaining six analytical parameters, Balanidae (and in one instance *Daphnia*) do not group with the remaining crustaceans. This result is more readily interpreted as anomalous behaviour of the sequence data of one organism than as evidence for crustacean paraphyly, as the original Pancrustacea hypothesis proposed. Morphological and combined analyses both identify the major groups Malacostraca and Branchiopoda, with the same basal splits (Leptostraca + Eumalacostraca and Anostraca + Phyllopoda, respectively) present in each cladogram. One of the most strongly supported groups within Crustacea, a union of cephalocarids and remipedes, is unexpected morphologically but has been detected in previous sequence analyses²⁵.

The analysis of deep evolutionary relationships has never been easy, especially when we attempt to make global statements about the most diverse metazoan phylum using a limited sample of creatures and characters. To our knowledge, this is the largest data set compiled for such an important group of animals and was analysed using unique cluster computer technology to provide a comprehensive hypothesis of arthropod relationships. Both quality and quantity of data were optimized to create precise and robust hypotheses. Such an approach is the first step towards comprehensive genomic comparisons and the understanding of the animal group that has dominated for the past 500 million years. □

Methods

Non-sequence data

Morphological and gene-order characters were analysed with NONA v. 2.0 (ref. 26) using a standard 1,000 replicates of random addition sequence, followed by TBR (tree bisection and reconnection) branch swapping. Multistate characters were unordered except where justified in character discussions.

Direct optimization

Phylogenetic analysis was performed by combining all of the available evidence and searching for the simplest (most parsimonious) explanation for character variation. This was accomplished with the program POY (ref. 17), which is explicitly designed to reconstruct phylogeny from diverse sources of information. Molecular data were optimized using the 'direct optimization' procedure¹⁶, which derives cladogram costs without multiple sequence alignment. This methodology accommodates sequence length variation as transformations involving the addition, deletion and substitution of

nucleotides, as opposed to the conjuring of unobservable 'gaps'. Direct optimization produces more parsimonious and more congruent results than multiple sequence alignment²⁷, and in a vastly accelerated time frame. POY minimizes the weighted number of evolutionary changes over the entire tree, working in a one-step fashion as opposed to the more classical two-step analyses (alignment + tree search).

Node support

Bremer support²⁸ was used as a measure for node support. This measure records the difference in length between the favoured tree and the shortest tree that does not contain a given group. As such, the Bremer value is a measure of how decisive the data are for a given branch of the tree.

Sensitivity analysis

To test node stability, 12 sets of parameters (gap/change quotients of 1, 2, 4 and transversion/transition quotients of 1, 2, 4 and ∞) were analysed for each of the ten partitions (eight loci, the combined molecular data, and the combined molecular + morphological data). Each of these 120 independent analyses was executed in parallel in the 256 processors, totalling 2 months of intense computation time using extremely effective tree search algorithms²⁹ and an aggressive search strategy, equivalent to 42 years of computing time if analyses had to be conducted in a single-processor machine. Parallelization was executed in groups of 32 processors, the point of maximum efficiency for marshalling jobs in our cluster. This kind of analysis explores the stability of data to analysis parameters, and therefore allows hypotheses to be formulated in a more robust way than traditional phylogenetic analysis.

The simultaneous analysis of multiple genes, morphology and mitochondrial gene order hinders application of different evolutionary models to independent partitions, and even more so when multiple parameters are explored. Therefore we opted for the simplicity of treating all partitions equally. Similarly, morphological and gene-order changes were weighted equally with insertion and deletion events.

Our 'optimal tree' is that which minimizes tree length (the most parsimonious) for all the data analysed in combination (total evidence) and for the parameter set that minimizes overall incongruence among partitions²⁴. In this case overall congruence is calculated as per the incongruence length difference (ILD) test³⁰, and it is optimized at an insertion/deletion cost equal to all other transformations (transversions or transitions).

Search strategy

Tree search commands executed in POY included random addition sequence followed by a fast parallelized tree-building step and by SPR (subtree pruning and regrafting) and TBR branch swapping. When classical swapping algorithms did not improve tree length, the data were submitted to several rounds of tree drifting and tree fusing²⁹ to decrease tree length. The entire search strategy was repeated up to 1,000 times or until the results converged on the same result at least three times in independent replicates. A typical command line used for a given stepmatrix (-molecularmatrix 111) is as follows:

```
poy-parallel-jobspernode 2 -noleading -norandomizeoutgroup
-molecularmatrix 111 -multibuild 10 -buildspr -buildtbr
-approxbuild -buildmaxtrees 1 -random 1000 -stopat 3 -minstop 10
-multirandom -sprmaxtrees 1 -tbrmaxtrees 2 -numdriftchanges 30
-driftspr -numdriftspr 10 -drifttbr -numdrifttbr 10 -0tchtrees
-holdmaxtrees 100 -controllers 32 -maxtrees 20 -treefuse
-fuselimit 10 -fusemingroup 5 -seed -1 'input 0les'
-prealigned 'input protein-coding 0les' > tot111.out 2>
tot111.err
```

The specific command lines and data files are provided as Supplementary Information.

Received 31 January; accepted 31 July 2001.

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Supplementary information is available on Nature's World-Wide Web site (<http://www.nature.com>) or as paper copy from the London editorial office of Nature.

Acknowledgements

We thank all those who have assisted us with morphological discussions, laboratory work (especially K. Demeo), collecting specimens, and given any other form of help or advice. D. Colgan and G. Wilson have been valued collaborators. S. Thurston provided technical illustration. J. Shultz and L. Prendini shared specimens and unpublished sequence data. Funding was mainly provided by the Fundamental Biology Program of NASA.

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Dissociation between hand motion and population vectors from neural activity in motor cortex

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The population vector hypothesis was introduced almost twenty years ago to illustrate that a population vector constructed from neural activity in primary motor cortex (MI) of non-human primates could predict the direction of hand movement during reaching^{1–6}. Alternative explanations for this population signal

have been suggested^{7,8} but could not be tested experimentally owing to movement complexity in the standard reaching model. We re-examined this issue by recording the activity of neurons in contralateral MI of monkeys while they made reaching movements with their right arms oriented in the horizontal plane—where the mechanics of limb motion are measurable and anisotropic. Here we found systematic biases between the population vector and the direction of hand movement. These errors were attributed to a non-uniform distribution of preferred directions of neurons and the non-uniformity covaried with peak joint power at the shoulder and elbow. These observations contradict the population vector hypothesis and show that non-human primates are capable of generating reaching movements to spatial targets even though population vectors based on MI activity do not point in the direction of hand motion.

Primary motor cortex (MI) has an important function in controlling visually guided limb movements, and a central problem in motor research has been to identify how neurons within MI participate in these tasks^{4,9}. Several studies have shown that the activity of individual neurons is sensitive to many different parameters related to target, hand and limb movement^{5,10–13}. However, it has been shown that if individual cells are represented as vectors, with direction defined by the cell's preferred direction (PD), the direction of movement in which the cell is maximally active) and magnitude defined as the cell's discharge rate for a given movement direction, the resulting vector sum (population vector) of all cell vectors is congruent with the direction of hand movement^{1–3,6}. This ability to predict hand motion has supported the idea that MI may reflect a higher level representation related to movement direction^{4,5}. Theoretical studies, however, have argued that neural activity in myriad coordinate frames related to sensory or motor features of the task would also produce population vectors that point in the direction of hand motion^{7,8,14}. This debate on the neural representation of movement in MI is important not only for understanding its role in movement planning and control, but also for understanding the computational processes performed by other regions of the central nervous system, such as the spinal cord. Although some deviations between the population vector and hand motion have been observed¹⁵, they have been small and difficult to interpret.

Considerable insight into human motor performance and learning has been gained from studies of planar limb movement where the arm is oriented in the horizontal plane, hand motion is generated only by flexion and extension motions at the shoulder and elbow, and the mechanics of movement can be easily estimated^{16–21}. The mechanics of these planar movements are anisotropic with large variations that are dependent on movement direction¹⁷. We addressed whether the activity of MI neurons at the population level was influenced by these mechanical anisotropies.

We trained monkeys to make planar movements with roughly straight hand trajectories to spatial targets (Fig. 1a). We recorded the activity of neurons in the left contralateral MI of monkeys while they made reaching movements with their right hand from a central target to eight spatial targets that were located on the circumference of a circle. The activity of 214 neurons was found to be unimodally tuned to the direction of movement (62, 22 and 130 in monkeys *a*, *b* and *c*, respectively). As shown previously, cell activity was broadly tuned to the direction of movement. Figure 1b shows the activity of a typical cell in MI during the task where maximal activity occurred when the monkey moved its hand to the right and towards itself (PD = 326°).

We constructed population vectors from our cell sample and compared these vectors to the actual directions of hand motion. Population vectors during movement tended to be biased towards one of two directions: away and left, or towards and right (Fig. 2a). Thirteen of the 16 population vectors did not point in the direction of hand motion (Fig. 2b). There was no significant correlation

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